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APPLICATION FOR PATENT

VIRTUAL MULTICHANNEL SPEAKER SYSTEM

Inventors: Michael I. Neidich
Paul R. Goldberg
Mitchell A. Golner

5 **Background of the Invention**

This invention relates generally to sound reproduction systems and, more specifically, to the enhancement of multichannel sound reproduction through improved speaker arrangement and the relation of this arrangement to audio signal processors and their algorithms.

10 A number of systems have been proposed for expanding the stereo image present in stereo source material. These systems employ a number of techniques and algorithms to expand the stereo image beyond the confines of the left and right speakers. Such systems have also been adapted to source material with more than two independent input channels, and for use with more than two speakers.

15 These find application in computer sound playback, home and car audio systems, and many other applications based on material from any of the many computer storage systems, video and audio cassettes, compact discs, FM broadcasts, and all other available stereo and multichannel media.

The generic stereo or two output channel arrangement of the prior art is shown in Figure 1. A listener 10 is positioned some distance D away from the midpoint between a pair of speakers 13 and 14. This midpoint is taken as the origin of the reference coordinates (x,y), with the X-axis extending as shown toward the primary listening area. In a general placement, each of the speakers, 13 and 14, will be different distance from the listener 10 and, in particular, a different distance from

20 each of the listener's ears 11 and 12. The signals to the right speaker 14 and the left

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speaker 13 are supplied from an audio signal processor 17 along lines 16 and 15, respectively. The signal processor produces the output signals along 15 and 16 based upon the audio signals input from lines 18. In the case of a 2 input, 2 output, or 2-2, signal processor, there are only two input lines 18.

5 In the simplest case, the signal processor is absent and a pair of input lines 18 from a stereo audio source are then the same as lines 15 and 16 and there is no enhancement of the stereo signals. When a signal is transmitted from a single speaker, say the right speaker 14, the listener identifies the location of the speaker as (x_r, y_r) based on the difference between what is perceived at the right ear 12 and
 10 what is perceived at the left ear 11. This difference in perception is due, firstly, to the difference in path lengths between the right speaker and the right ear, d_{rr} and between the right speaker and the left ear, d_{rl} , and to a difference in audio level. This difference produces a corresponding delay in the signal at the left ear as it must propagate the additional distance $\Delta d_r = d_{rl} - d_{rr}$. But there are also additional effects:
 15 These arise as the head of the listener 10 is not acoustically transparent to the sound waves and will alter them as they propagate around the head to the left ear 11. This filtering effect is described in terms of Head Related Transfer Functions (HRTFs). This combination of signal delay and alteration as perceived by the listener contribute to how the source of the sound is identified as being at the point (x_r, y_r) .

20 To produce a sound that the listener will perceive as being located at an arbitrary point (x, y) , a speaker 19 would ideally, but impractically, be placed at each such position (\hat{x}, \hat{y}) . To produce the sounds across the entire front field of the listener, such as is desired for home theater, computer games, or many other uses, would therefore require a vast number of speakers and a corresponding number
 25 of independent signals for this surround sound or multichannel effect. To mimic this effect, the psycho-acoustical mechanisms that allow the listener to fix the location of a sound source can be exploited through delay and HRTFs.

A number of different algorithms exist for this purpose and are widely know in the art. Examples and sources include Dolby Laboratories, Q-Sound Corporation, Spatializer Corporation, Aureal Semiconductor, Harman International,
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30 location of the speakers 13 and 14 as well as the actual speakers themselves. For the

various processing blocks 23, 24, 25, and 26 to provide the correct delays, HRTFs, and so on requires the algorithm to assume a particular speaker separation and alignment modeled on point-like speakers. It must also make a series of assumptions about speaker response, particularly about the differential response of one speaker relative to the other.

As these assumptions are built into the signal processor, it is important that the speakers are spaced correctly and, preferable, slightly above the listener. For the proper psycho-acoustical response, the physical speaker separation is more important than the Y location of the listener, with the listener's X position even less critical. Users frequently place speakers in an arbitrary manner for any number of practical or aesthetic reasons, because the size or purpose of the correct physical separation is not known, or based on the incorrect assumption that a wider physical separation produces a better result. Additionally, for some computer monitors and other uses, the speakers are often fixed, but in a position that may be incorrect as the algorithm used may have been based on the speaker position of, say, a car. These defects undermine the algorithm at the core of the signal processor and are a serious limitation in the prior art.

The alignment, or azimuthal angle, or the speaker axis also affects the sound received by the listener. The above example of speaker placement in a car compared to that in a home computer system is also illustrative of this problem: Car speakers are often placed in the doors of the automobile where the sound will come from the listener's sides, while personal computer applications usually place the speaker to the front of the listener. Aside from any change in relative delay of amplitude this may cause, these two placements will require different HRTFs as the sound will propagate around the listener on a different path. Even with the alignment of the application for which the algorithm was designed, aligning one speaker askew to the other speaker will create another differential response that will undermine the algorithm.

The assumptions about the speakers themselves include idealizing them as having the same response to a given input signal. Whether through using

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Similarly, such multichannel or matrix sound system would benefit from an increase in the number of actual speakers, although a method would be needed to produce the signals suitable for these extra speakers. Once again, proper placement of these speakers is needed for the best results.

15 Other objectives are to present a speaker mechanism that holds the speakers in a set spatial relationship, either fixed or adjustable to each other and including a sensor mechanism to provide data about this relationship and other relative speaker information. A further objective is to use this information to effect variation in the algorithm employed by the audio signal processor.

20 An additional objective of the present invention is to extend these other objectives beyond two channel stereo to matrix or multichannel audio systems by extending the same techniques to rear sound channels, and, furthermore, by such an application to produce a virtual rear center channel when only a left and right rear channel signal are provided.

25 A further object is to use such algorithms to provide audio signals to
an even greater number of speaker pairs to flood an enclosed listening space with
sounds from a greater number of directions.

Summary of the Present Invention

These and additional objects are accomplished by the various aspects of the present invention, wherein, briefly and generally, audio reproduction is improved by statically or dynamically conforming the signal processing to specific speaker characteristics and/or arrangements. According to one such aspect, one or more dynamic signal processing algorithms driving two or more speakers are altered in response to the relative physical characteristics or arrangements of these speakers, where parameter information for these algorithms is either factory set, user input, or automatically supplied to the processor. Examples of such relative speaker differences include speaker spacing or alignment, speaker or enclosure compliance, and enclosure configuration. Another aspect is to alter the processing algorithms in response to common speaker characteristics for certain conditions of input signals. An example of this aspect is to alter the signal processing to improve bass response as a function of bass content in the signals being presented to the speakers and speaker size as well as relative speaker position.

Additional objects, advantages, and features of the present invention will become apparent from the following description of its preferred embodiments, which description should be taken in conjunction with the accompanying drawings.

Brief Description of the Drawings

- Figure 1 shows a prior art stereo arrangement.
- Figure 2 is a block diagram for an example of a prior art signal processor.
- Figure 3 shows a preferred embodiment of some aspects of the present invention.
- Figure 4 is a block diagram for a signal processor in Figure 3.
- Figure 5 is a block diagram of these aspects applied to a personal computer.
- Figure 6 shows the relation of a speaker enclosure described in the text and its relation to a video monitor.

Figure 7 is a flow chart for determining the correct choice of algorithm in a discrete embodiment of the present invention.

Figure 8 shows two embodiments of the invention for a audio source with rear sound channels.

5 Figure 9a shows a 5.1 channel home sound system as commonly arranged in the prior art.

Figure 9b shows a 5.1 channel home sound system employing one aspect of the present invention.

10 Figure 10 shows another embodiment with four signal processors and four sets of speakers.

Figure 11 shows an additional embodiment with four signal processors and two sets of speakers.

Description of the Preferred Embodiments

15 ① An embodiment of the present invention uses single driver speakers to improve spatial imaging by eliminating crossover network manufacturing variations in an arrangement of the speaker spacing with automatic adjustment of the digital signal processing algorithm based on the speaker spacing as sensed by the special speaker housings and connecting sleeve. ② Another aspect allows information on speaker spacing to be factory set or input by the user so that the signal processor
 20 may still be used with a pair of speakers not connected in a way that automatically provides this information. ③ Conversely, a further aspect is a speaker enclosure that uses two single driver speakers in identical housings, joined by a mechanism that enables the spacing between the speakers to be set to match the width of the underlying supporting surface, such as a TV or computer monitor, by using a joining
 25 mechanism that allows the spacing to be optimized.

Figure 3 shows several aspects of the present invention in this embodiment. As in Figure 1, a listener 10 is located in front of a pair of speakers 13 and 14. The speakers are separated by a distance s from each other with their midpoint a distance D from the listener. This midpoint is taken as the origin of the

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embodiments below, only the speaker spacing is given as an explicit input parameter as this is both an important example and is easily discussed and shown in the figures. More general embodiments may employ a higher dimensional space of input parameters. For example, the signal processor described above may be employed with a pair of speakers not in the described enclosure. In this case, variations in speaker and enclosure compliance, differences in enclosure configuration, and azimuthal alignment of speaker axes could also be entered into the algorithms in addition to inter-speaker separation. Preferable these and other parameters used for dynamic processing adjustments are made automatically through input 31, although manual input 32 allows them to be entered along with other information such as choice of matrix decoding scheme. The option of manual input allows the signal processor to be used with prior art speakers.

By using the automatic supply of parameters, such as inter-speaker separation s in the embodiment of Figure 3, this aspect of the present invention allows for the automatic dynamic processing of input signals to drive the speakers based on parameters determined by the relative characteristics of the speakers. The actual parameters may be either static, such as speaker spacing, or dynamic, such as speaker compliance. A familiar prior art example of parameters that may be altered is the combination of volume and balance controls: The volume control is an input common to both channel which sets the overall loudness, while the balance control determines the relative loudness of the two channels. The balance is an example of a parameter based on relative characteristics. The sort of processing variations under consideration here are dynamic alterations in the processing algorithms affecting properties such as the phase of the signals within the processor. Aside from applications for enhanced stereo employing HRTFs and other enhancement methods, standard multichannel sound reproduction could also benefit from these techniques to offset problems due to those relative speaker differences and placement problems.

As discussed above in the Background, it is this proper physical speaker separation for a processor's algorithm that largely determines the

effectiveness of that algorithm. It is more important than the listener's Y position or the even less critical X position. To exactly position the location of speakers 13 and 14, they would, as an idealization, be point sources. For this reason, one preferred embodiment employs a single driver speaker for each of 13 and 14. Since it is physically impossible to move the amount of air needed for low frequencies with small drivers, this results in a trade off between maximizing the effectiveness of the stereo enhancement of the DSP 37 and the frequency response of larger and/or multiple speakers. Another standard solution to this problem is to employ a separate subwoofer for low frequencies to exploit the psycho-acoustical effect that these low frequencies can not be localized as well as higher frequencies. This may be realized with a ported enclosure for bass.

Another solution to the lack of bass response for smaller speakers is an aspect of the present invention that can be incorporated within the embodiment of Figure 3 or other embodiments. This would also involve automatic dynamic processing of the input signals within the signal processor, but now to improve bass response based upon speaker size as well as relative speaker position. By driving the speakers in unison, the effective bass response is improved since, functioning together, they can move a larger quantity of air. Above a chosen frequency, the individual signals would maintain the values they would have without the incorporation of this aspect. Below a second lower frequency, say 100Hz, both channels would be provided the same output signals with the same phase. In between these two frequencies, the individual signals would transition between these two states in a smooth manner, so that there would be no abrupt change at the transition frequencies. The choice of transition frequencies and characteristics could be chosen based on speaker characteristics combined with the de-localization effect of lower frequencies. In this way, a digital signal processor may be used as a crossover network with phase adjustment to enable using single or multi-driver speakers more effectively for virtual 3D and other sound applications.

The described invention can be used to advantage in any of the applications for enhanced stereo. These include the home audio uses of rendering

surround sound from stereo and matrix stereo sources, such as records, reel-to-reel and cassette tapes, VHS video cassettes, compact discs (CDs), Laserdiscs, or DVDs, and car and RV audio rendering from stereo media such as tape, radio broadcasts, CDs, or VHS video cassettes. For illustrative purposes, the next part of the discussion will, however, largely focus on computer sound playback from any of the standard sources. To simplify the figures and discussion, these again mainly use speaker separation as the single input parameter, although the other parameters described above and in the following may be included in other embodiments. Additionally, although the signal processor DSP 37 is a digital device, analog techniques could also be utilized in other embodiments.

In this context of a PC, Figure 5 shows a block diagram of a preferred embodiment. The audio source 40, such as a PC sound card, supplies a left and right signal on lines 18 to the DSP 37. As these may be encoded by any number of the standard schemes available, the DSP 37 will also include the corresponding decoding process in connection with its virtual multichannel algorithms. To allow, as a sub-aspect of the present invention, the use of DSP 37 with a standard pair of powered speakers, input 32 allows for the physical speaker separation to be input manually. In a more general embodiment, other information, say, related to room acoustics, such as distance to rear front walls, reverb, speaker response, variations in HRTFs, or choice of decoding algorithm, could also be supplied at input 32. As shown, however, the preferred embodiment does supply the modified left and right signals L' 15 and R' 16 to their respective speakers 13 and 14. The data on the separation of the speakers is given to the DSP 37 from the speaker enclosure along line 31. In response to this input, the processing algorithm is adjusted for the speaker separation s , so that $L' = L'(s)$ and $R' = R'(s)$.

Figure 6 shows another sub-aspect of the present invention in the preferred embodiment described above. The speaker enclosure is shown as 30, 30', and 30'' adjusted to respective separations s , s' , and s'' . By having the two single drivers in matched housings, relative compliance and alignment variations are minimized. The enclosure joins them by a mechanism that enables the spacing

between the speakers to be set to match the width of the underlying supporting surface, typically a TV or computer video monitor. The joining mechanism contains sensors to enable the DSP algorithm to be optimized for the specific spacing. It also serves several practical purposes: The first of these is that of keeping the separation of the speakers within the optimal range for stereo enhancement algorithms, which is somewhat larger than the width of the listeners head. Another is that it will place the speakers in a better vertical alignment, namely, even with or slightly higher than the listener. Finally, it solves the problem of where to place the speakers, a practical difficulty that is often the cause of incorrect speaker placement, by transferring them from the desktop or other valuable area to a space normally not used.

Although the discussion so far has implicitly assumed that the speaker geometry is continuously adjustable and that the algorithms would correspondingly be continuously variable in response, in the preferred embodiment this is not the case. To have the DSP algorithms continuously adjustable would require a more complicated and, consequentially, more expensive implementation. Instead, the preferred embodiment has the algorithm set for a number of discrete values for speaker spacing. By including enough different values, this serves as a practical compromise between cost and complexity. These preset values can be set for a number of standard speaker spacings, say 14 inches, 17 inches, and so on, corresponding to popular monitor sizes on top of which the enclosure would be placed. The DSP could then determine by a look up table, a predetermined table of constants, and/or other processing variables which of the discrete algorithms is appropriate for the spacing range into which the speakers fall.

Figure 7 shows a flow chart for a simplified example of the process. At step 100, the value of s is provided. This can be provided automatically, as in the preferred embodiments described, or entered manually by the user. For the cases described below with more than one pair of speakers, s would be a vector containing the various relative separations of the speakers. At step 110, the value range into which s fits is determined. This is chosen to be one of a set of ranges corresponding to spacing values appropriate to the application. In this example, three ranges

corresponding 14, 17, and 21 inches are used: For $s < 15$ ", an algorithm based on 14" is used in step 114; if $15" \leq s < 19$ ", an algorithm instead based on 17" is used in step 117; and when $19" \leq s$, step 121 uses an algorithm based on a 21" separation. Any of the standard enhanced stereo algorithms appropriate to these values could then be employed.

A variation on the above embodiments is the case of the speakers in a constant relationship to each other. The virtual multichannel algorithm can then be conformed to this fixed difference. In this way, an algorithm with parameters for this specific configuration may be incorporated into a circuit for use with a specified speaker configuration, thereby allowing these enhancement parameters to be factory set.

Other aspects of the present invention incorporate such algorithms in the production of signals for rear speakers, which, in one embodiment, also use a speaker enclosure to provide for automatic adjustment of a digital signal processing algorithm. These aspects can be used with sources which provide rear audio signals and also to provide a virtual rear center channel for 5.1 channel home cinema and other applications. A further extension are aspects that apply these signal processors and speaker enclosures to produce audio signals for side speakers to increase sound immersion. The inclusion of side speakers allows for a smoother transition between front sourced sounds and rear sourced sounds in addition to the more accurate placement of sound to the sides.

A number of personal computer audio sources have a provision for rear sound channels. Figure 8a shows such a situation where the audio source 40 now has left and right rear signals on lines 65 and 66 to respective speakers 63 and 64. The front audio channels are as before in Figure 5. This allows the use of DSP 37 and speaker enclosure 30 for the front channels, where the listeners ability to localizes a sound is more acute, while taking advantage of provided rear channels signals. It should be noted that although the figures refer to powered speakers, since these are common in the personal computer examples being used, other embodiments need not use these and could employ other means for amplification.

Figure 8b is a preferred variation of the arrangement of Figure 8a. Even though hearing from the rear is less highly localized by the listener, including a second DSP for the rear, DSP_s 67, will produce a virtual multichannel surround sound environment from that direction. This embodiment will employ a speaker enclosure 60 with input 61 back to DSP_s 67 for the rear for automatic adjustment of DSP_s's algorithm, just as the front speaker enclosure 30 does for the front channel processor, now labeled DSP_N 37. To further improve the sound environment, as the sound waves will propagate around the listener differently from the rear than from the front, the preferred embodiment will employ HRTFs appropriate to a rear speaker position in DSP_s 67. Although Figure 8b shows the front enclosure 30 and rear enclosure 60 with the same spacing, this is just for illustrative purposes as these spacing are independent and need not be the same. A unified embodiment could combine DSP_s 67 and DSP_N 37 into a single unit taking both inputs 18 and inputs 68 from audio source 40 as well as the inputs 31 and 61 from respective enclosures 30 and 60.

An embodiment intermediate between Figures 8a and 8b is also possible, where DSP_s 67 is employed, but with speakers 63 and 64 not contained in an enclosure 60 and information on rear speaker geometry now from input 62. This could be due to practicalities of speaker placement or to save on equipment costs. Additionally, any of these variations on Figure 8b could additionally use the separation between the front and the back speaker pairs to modify the algorithms in DSP_s 67 and DSP_N 37 to optimized the sound environment based on this additional input.

Moving away from the generic example discussed in terms of a PC embodiment, the use of an arrangement enabling adjustment of the speaker spacing with automatic adjustment of the DSP algorithm can be applied to the more specific example of home theater sound systems. Figure 9a shows a prior art arrangement for a 5.1 channel system. This provides for 5 channels of audio sound, with the 1 referring to a non-directional low frequency channel. These five channels are distributed among left, center, and right front channels with respective speakers 71,

72, and 73, and left and right rear, or surround, channels with respective speakers 74 and 75. One aspect of the current invention is employed in a preferred embodiment shown in Figure 9b. Speakers L_s 74 and R_s 75 are now in enclosure 76 connected to DSP 77 in the manner described above with respect to Figures 5 and 8b. This will now produce a virtual multichannel sound environment for the rear or surround channels, and can produce a virtual center rear channel to correspond to or complement the actual front center channel. An embodiment intermediate between Figures 9a and 9b is again possible, using DSP 77 but with separate speakers L_s 74 and R_s 75 not in a single enclosure 76, information on the geometry of these speakers input at 78.

Returning to the PC example of an audio source with two front and two rear output signals, Figures 10 and 11 present embodiments of two further aspects of the present invention which employ four DSPs. Even with the virtual multichannel enhancement of the present invention applied to both front and rear channels as in Figure 9b, there may still be a large physical gap between the front speaker enclosure 30 and the rear enclosure 60. Representation of sound from the listener's sides will not be as realistic as from placement of actual speakers to the listener's left and right. A preferred embodiment for such an arrangement is shown in Figure 10.

Figure 10 starts from the arrangement of Figure 8b, but then adds on two additional speaker enclosure/DSP pairs: DSP_E 82 and enclosure 84 to the right, or east, to produce sound from speakers 86 and 88, and DSP_W 81 and enclosure 83 to the left, or west, to produce sound from speakers 85 and 87. DSP_E 82 and DSP_W 81 receive their input from both front and rear channels. This use of multiple two speaker enclosures will flood the enclosed listening space and produce a smoother transition between front and rear sound location as well as better definition of side source sounds. As with the front and rear signal processors, DSP_E 82 and DSP_W 81 will preferably employ HRTFs appropriate for their relation to the listening area. Although the four pairs of speakers are shown in enclosures 30, 60, 83, and 84, other embodiments could replace any or all of these with just a generic pair of

signals are summed and returned to only the front pair of speakers 13 and 14 and the rear pair of speakers 63 and 64. The inputs from enclosures 30 and 60 to the DSPs 37, 67, 81, and 82 are suppressed to simplify the drawing.

5 Adders 91-94 combine signals from the side DSPs with the front and rear DSPs. For example, the left front signal on 15 is now the sum of the left signal from the front DSP 37 and the right signal of the right DSP 81. The result is more wrap around to the sides. The resultant signals are given by:

$$\begin{aligned} L &= k_{1a}LN + k_{1b}RW \\ R &= k_{2a}RN + k_{2b}LE \\ 10 \quad L_s &= k_{3a}LS + k_{3b}LW \\ R_s &= k_{4a}RE + k_{4b}RS. \end{aligned}$$

The k s are constants introduced to allow the relative amplitudes to be varied according to the acoustic environment or other needs. For example, in the symmetric situation shown in Figure 11 placed in a symmetric environment, the
15 choice $k = 1/\sqrt{2}$ for all of the k s gives a symmetric output for symmetric adder inputs and results in unit output amplitude for unit adder input amplitudes. This will have much the same advantage as the arrangements discussed with respect to Figure 10, but in situations where the additional speakers are not desirable or practical.

20 Various details of the implementation and method are merely illustrative of the invention. It will be understood that various changes in such details may be within the scope of the invention, which is to be limited only by the appended claims.